

SÈRIE 4

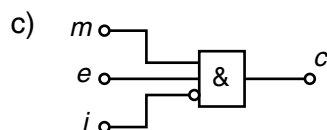
Primera part

Exercici 1

Q1 c Q2 a Q3 a Q4 a Q5 d

Exercici 2

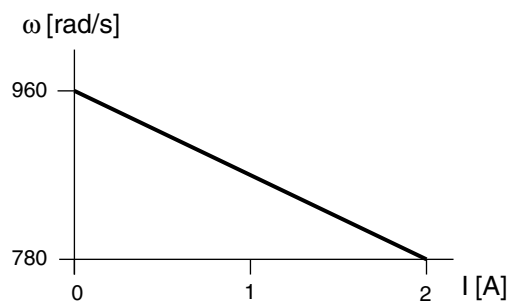
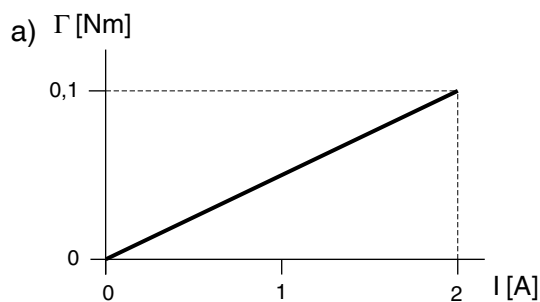
	<i>e</i>	<i>i</i>	<i>m</i>	<i>c</i>	
	0	0	0	0	
	0	0	1	0	
	0	1	0	0	
a)	0	1	1	0	b) $c = e \cdot \bar{i} \cdot m$
	1	0	0	0	
	1	0	1	1	
	1	1	0	0	
	1	1	1	0	



Segona part

OPCIÓ A

Exercici 3



$$\left. \begin{aligned}
 \text{b) } \Gamma &= c \cdot I = 0,05 \text{ N} \cdot \text{m} \\
 \omega &= \frac{U - R \cdot I}{c} = 870 \text{ rad/s}
 \end{aligned} \right\} \rightarrow P_m = \Gamma \cdot \omega = 43,5 \text{ W}$$

$$P_e = U \cdot I = 48 \text{ W}$$

c) $\eta = \frac{P_m}{P_e} = 0,9063 \rightarrow \eta = 90,63\%$

Exercici 4

$$\begin{aligned} \text{a) } \sum F_{\text{verticals}}|_{\text{cabina}} &= 0 \rightarrow F_{\text{cable}} - mg = 0 \rightarrow F_{\text{cable}} = mg = 10,79 \text{ kN} \\ \sum M|_{\text{politija}} &= 0 \rightarrow 2F_{\text{cable}} - F_{\text{ch}} = 0 \rightarrow F_{\text{ch}} = 2F_{\text{cable}} = 21,58 \text{ kN} \end{aligned}$$

$$\text{b) } \rho_{\text{int}} = \frac{F_{\text{ch}}}{S_{\text{int}}} = \frac{F_{\text{ch}}}{\pi \left(\frac{d_{\text{int}}}{2} \right)^2} = 2,747 \text{ MPa}$$

$$\text{c) } \sigma_{\text{tija}} = \frac{F_{\text{ch}}}{S_{\text{tija}}} = \frac{F_{\text{ch}}}{\pi \left(\frac{d_{\text{tija}}}{2} \right)^2} = 6,502 \text{ MPa}$$

$$\text{d) } q = S_{\text{int}} \frac{v}{2} \rightarrow v = \frac{2q}{S_{\text{int}}} = 1,528 \text{ m/s}$$

OPCIÓ B

Exercici 3

$$\text{a) } v = \frac{c_{\text{ev}}}{h \cdot b} = 280 \text{ m/h}$$

$$\text{b) } c_{\text{c}} = \rho_{\text{c}} \cdot \rho_{\text{c}} \cdot V = 130,9 \text{ MJ}$$

$$\text{c) } \eta = \frac{E_{\text{mot}}}{c_{\text{c}}} = \frac{P_{\text{mot}} \cdot t_{\text{au}}}{c_{\text{c}}} = 0,2805$$

Exercici 4

$$\text{a) } I = U/R = 0,5 \text{ A}; \quad P = U^2/R = 6 \text{ W}$$

$$\text{b) } E_{\text{pols}} = P \cdot t_{\text{p}} \rightarrow E = E_{\text{pols}} \cdot n_{\text{pols}} = P \cdot t_{\text{p}} \frac{1}{T} = 3 \text{ J}$$

$$\text{c) } P_{\text{mit}} = \frac{E}{1} = 3 \text{ W}$$